# **VS-GSWG** Swing Gate Operator Installation Guide





### **Table of Contents**

Pre-installation Information
Always Check the Gate's Action
Gate Operator Classifications
Approved Obstruction Detection Devices
Safety Information and Warnings.
Regulatory Warnings.
Wiring Specifications
AC Power Wiring
DC Control and Accessory Wiring
Mounting Pad Installation
Gate Preparation
Mounting Specifications
Operator Preparation
Vent Plug Installation
Gate Arm Installation
Operator Setup
Farth Ground
Open and Close Limit Adjustment
Limit Nuts Rough Adjustment
Limit Nuts Fine Adjustment
Setting Speeds using LSO-2 & LSC-2
Torque Limiter Adjustment.
Controller Features
Indicator Descriptions.
Terminal Descriptions 10
Operator Accessory Connections
Entering Programming Mode
Exiting Programming Mode 12
Programming Keystrokes
Left or Right Hand Operation
Dual Gate Enable
Auto Close Timer
Run Alarm and Pre-start Alarm1
Run Alarm and Pre-start Alarm.    13      Maximum Open Direction Current Setting.    13
Run Alarm and Pre-start Alarm
Run Alarm and Pre-start Alarm.       10         Maximum Open Direction Current Setting.       11         Maximum Close Direction Current Setting       12         Advanced Controller Programming       14
Run Alarm and Pre-start Alarm.       10         Maximum Open Direction Current Setting.       11         Maximum Close Direction Current Setting       12         Advanced Controller Programming       14         Entering Advanced Programming Mode       14
Run Alarm and Pre-start Alarm.       10         Maximum Open Direction Current Setting.       11         Maximum Close Direction Current Setting       12         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Ruther Insult Seture       14
Run Alarm and Pre-start Alarm.       10         Maximum Open Direction Current Setting.       11         Maximum Close Direction Current Setting       12         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14
Run Alarm and Pre-start Alarm.       10         Maximum Open Direction Current Setting.       11         Maximum Close Direction Current Setting       12         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Mode       14         Stagger Mode       14
Run Alarm and Pre-start Alarm.       10         Maximum Open Direction Current Setting.       11         Maximum Close Direction Current Setting       12         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Auxiliary Relay Mode       14
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       13         Maximum Close Direction Current Setting       13         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Auxiliary Relay Mode       14         Reverse Delay Time       14
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       13         Maximum Close Direction Current Setting       13         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Reverse Delay Time       14         Brake Delay Time       15
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Auxiliary Relay Mode       14         Brake Delay Time       15         Constant Pressure Mode       14
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       15         Reverse Delay Time       15         Brake Delay Time       15         Constant Pressure Mode.       14         Shadow Loop Open Prevention.       14
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       14         Brake Delay Time       15         Brake Delay Time       16         Shadow Loop Open Prevention.       16         Shadow Loop Open Prevention.       16
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       14         Brake Delay Time       15         Constant Pressure Mode.       14         Shadow Loop Open Prevention.       15         Reset Cycle Count       16         Maintenance Alert Trigger       16
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       14         Brake Delay Time       15         Brake Delay Time       15         Shadow Loop Open Prevention.       15         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position.       16         Autitalized Enable       16
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       14         Reverse Delay Time       14         Constant Pressure Mode.       15         Shadow Loop Open Prevention.       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Maintenance Alert Trigger       16         Anti-tailgate Enable       16         Badio Enable       16
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       13         Maximum Close Direction Current Setting       13         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Brake Delay Time       15         Brake Delay Time       15         Brake Delay Time       16         Shadow Loop Open Prevention       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Radio Enable       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         Radio Enable       16
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Brake Delay Time       14         Constant Pressure Mode       15         Reset Cycle Count       16         Maintenance Alert Trigger       16         Maintenance Alert Trigger       16         Anti-tailgate Enable       16         Radio Enable       16         Anti-tailgate Enable       16         Anti-tailgation       16         Anti-tailgation       16         Anti-tailgation       16         Anti-tailgation       16         Anti-tailgation       16         Anti-tai
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Brake Delay Time       14         Constant Pressure Mode       15         Shadow Loop Open Prevention       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Maintenance Alert Trigger       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         Anti-na Installation       16         Radio Transmitter Learn       17         Radio Transmitter Delete       17
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Brake Delay Time       14         Brake Delay Time       15         Constant Pressure Mode       15         Shadow Loop Open Prevention       16         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Radio Transmitter Learn       17         Radio Transmitter Delete       17         MGT Obstacle Transmitter Learn       17
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Brake Delay Time       15         Constant Pressure Mode       15         Shadow Loop Open Prevention       16         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Radio Transmitter Learn       17         Radio Transmitter Delete       17         MGT Obstacle Transmitter Delete       17
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       14         Brake Delay Time       15         Brake Delay Time       15         Constant Pressure Mode.       14         Shadow Loop Open Prevention.       16         Reverse Delay Time       16         Constant Pressure Mode.       16         Shadow Loop Open Prevention.       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position.       16         Anti-tailgate Enable       16         Radio Transmitter Delete       17         Radio Transmitter Delete       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       16         Reverse Delay Time       15         Brake Delay Time       16         Constant Pressure Mode.       16         Shadow Loop Open Prevention.       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position.       16         Anti-tailgate Enable       16         Radio Transmitter Learn       17         Radio Transmitter Learn       17         MGT Obstacle Transmitter Learn       17         Motor Type Selection       17         Motor Type Selection       17         Motor Type Selection       17
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time.       14         Auxiliary Relay Mode.       14         Reverse Delay Time       15         Brake Delay Time       16         Constant Pressure Mode.       16         Shadow Loop Open Prevention.       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position.       16         Anti-tailgate Enable.       16         Antenna Installation.       16         Radio Transmitter Delete       17         Radio Transmitter Delete       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17         Reset Controller to Factory Defaults       17         Loop Layout Illustration       18
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Reverse Delay Time       14         Constant Pressure Mode       15         Shadow Loop Open Prevention       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Maiotenance Alert Trigger       16         Madio Enable       16         Radio Enable       16         Radio Transmitter Learn       17         MGT Obstacle Transmitter Delete       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17         Reset Controller to Factory Defaults       17         Katop Layout Illustration       18
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming.       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Reverse Delay Time       14         Constant Pressure Mode       15         Brake Delay Time       16         Constant Pressure Mode       16         Shadow Loop Open Prevention       16         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         Anti-tailgate Enable       17         Radio Transmitter Learn       17         MGT Obstacle Transmitter Learn       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17         Reset Controller to Factory Defaults       17 <t< td=""></t<>
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Reverse Delay Time       14         Constant Pressure Mode       14         Shadow Loop Open Prevention       15         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Radio Transmitter Learn       17         Radio Transmitter Delete       17         MGT Obstacle Transmitter Learn       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17         Motor Type S
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Reverse Delay Time       14         Constant Pressure Mode       15         Brake Delay Time       16         Constant Pressure Mode       16         Shadow Loop Open Prevention       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         MGT Obstacle Transmitter Learn       17         MGT Obstacle Transmitter Delete       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17         Reset Controller to Factory Defaults       17
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       14         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Reverse Delay Time       14         Brake Delay Time       15         Constant Pressure Mode       15         Shadow Loop Open Prevention       16         Maintenance Alert Trigger       16         Maintenance Alert Trigger       16         Maintenance Alert Trigger       16         Anti-tailgate Enable       16         Anti-tailgate Enable       16         Antenna Installation       16         Radio Transmitter Delete       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection       17         Reset Controller to Factory Defaults       17         Motor Type Selection       17         Motor Type Selection       17         Moto
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting       1         Advanced Controller Programming       1         Entering Advanced Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Mode       1         Auxiliary Relay Mode       1         Reverse Delay Time       1         Brake Delay Time       1         Brake Delay Time       1         Constant Pressure Mode       1         Shadow Loop Open Prevention.       1         Reset Cycle Count       1         Maintenance Alert Trigger       1         Mid-travel Stop Position.       1         Anti-tailgate Enable       1         Anti-tailgate Enable       1         Radio Transmitter Delete       1         MGT Obstacle Transmitter Learn       1         MGT Obstacle Transmitter Learn       1         Motor Type Selection       1         Reset Controller to Factory Defaults       1         Loop Layout Illustration       1         Photoeye Installation Illustration       2         Optional In-
Run Alarm and Pre-start Alarm.       13         Maximum Open Direction Current Setting.       14         Maximum Close Direction Current Setting       15         Advanced Controller Programming       14         Entering Advanced Programming Mode       14         Maximum Run Time       14         Single Button Input Setup       14         Stagger Mode       14         Stagger Delay Time       14         Auxiliary Relay Mode       14         Reverse Delay Time       14         Brake Delay Time       14         Brake Delay Time       15         Brake Delay Time       16         Shadow Loop Open Prevention.       16         Reset Cycle Count       16         Maintenance Alert Trigger       16         Mid-travel Stop Position.       16         Anti-tailgate Enable       16         Anti-tailgate Enable       17         MGT Obstacle Transmitter Delete       17         Motor Type Selection.       17         Reset Controller to Factory Defaults       17
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming       1         Advanced Controller Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Mode       1         Auxiliary Relay Mode       1         Reverse Delay Time       1         Brake Delay Time       1         Constant Pressure Mode       1         Constant Pressure Mode       1         Reset Cycle Count       1         Maintenance Alert Trigger       1         Mid-travel Stop Position       1         Anti-tailgate Enable       1         Radio Transmitter Learn       1         Radio Transmitter Delete       1         MGT Obstacle Transmitter Delete       1         MGT Obstacle Transmitter Delete       1         Motor Type Selection       1         Reset Controller to Factory Defaults       1         Loop Layout Illustration       1         MGT Obstacle Transmitter Delete       1         Motor Type Selection       1         Reset Cont
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming       1         Advanced Controller Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Mode       1         Auxiliary Relay Mode       1         Reverse Delay Time       1         Brake Delay Time       1         Constant Pressure Mode       1         Constant Pressure Mode       1         Reset Cycle Count       1         Maintenance Alert Trigger       1         Mid-travel Stop Position       1         Anti-tailgate Enable       1         Radio Transmitter Learn       1         Radio Transmitter Delete       1         MGT Obstacle Transmitter Delete       1         MGT Obstacle Transmitter Delete       1         Motor Type Selection       1         Reset Controller to Factory Defaults       1         Loop Layout Illustration       1         Safety Edge Layout Illustration       1         Optional In-Cabinet Heater       2         Open
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming.       1         Entering Advanced Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Mode       1         Stagger Delay Time       1         Auxiliary Relay Mode       1         Reverse Delay Time       1         Brake Delay Time       1         Constant Pressure Mode       1         Shadow Loop Open Prevention       1         Reset Cycle Count       1         Maintenance Alert Trigger       1         Mid-travel Stop Position       1         Anti-tailgate Enable       1         Radio Transmitter Delete       1         MGT Obstacle Transmitter Learn       1         MGT Obstacle Transmitter Delete       1         Motor Type Selection       1         Reset Controller to Factory Defaults       1         Loop Layout Illustration       1         Photoeye Installation Illustration       2         Optional In-Cabinet Heater       2         Ope
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming.       1         Entering Advanced Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Mode       1         Auxiliary Relay Mode       1         Reverse Delay Time       1         Constant Pressure Mode       1         Shadow Loop Open Prevention.       1         Reset Cycle Count       1         Maintenance Alert Trigger       1         Mid-travel Stop Position.       1         Anti-tailgate Enable       1         Radio Transmitter Delete       1         MGT Obstacle Transmitter Learn       1         MGT Obstacle Transmitter Delete       1         MGT Obstacle Transmitter Delete       1         Motor Type Selection.       1         Reset Controller to Factory Defaults       1         Loop Layout Illustration       2         Optional In-Cabinet Heater       2         Open Button       2         Open Button       2         Stop Button
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming.       1         Entering Advanced Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Delay Time       1         Auxillary Relay Mode       1         Brake Delay Time       1         Brake Delay Time       1         Constant Pressure Mode       1         Shadow Loop Open Prevention       1         Reserse Delay Time       1         Reset Cycle Count       1         Maintenance Alert Trigger       16         Mid-travel Stop Position       16         Anti-tailgate Enable       16         Antion Installation       16         Radio Transmitter Learn       17         Radio Transmitter Delete       17         MGT Obstacle Transmitter Learn       17         Reset Controller to Factory Defaults       17         Loop Layout Illustration       18         Safety Edge Layout Illustration       19         Photoeye Installation Illustration       22
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming       1         Entering Advanced Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Delay Time       1         Auxiliary Relay Mode       1         Reverse Delay Time       1         Brake Delay Time       1         Constant Pressure Mode.       1         Shadow Loop Open Prevention.       1         Reverse Delay Time       1         Reverse Delay Time       1         Maintenance Alert Trigger       1         Mid-travel Stop Position.       1         Anterna Installation.       1         Anterna Installation.       1         Radio Transmitter Delete       1         MGT Obstacle Transmitter Delete       1 <t< td=""></t<>
Run Alarm and Pre-start Alarm.       1         Maximum Open Direction Current Setting.       1         Maximum Close Direction Current Setting.       1         Advanced Controller Programming       1         Entering Advanced Programming Mode       1         Maximum Run Time       1         Single Button Input Setup       1         Stagger Delay Time.       1         Auxiliary Relay Mode.       1         Reverse Delay Time       1         Brake Delay Time       1         Constant Pressure Mode.       1         Constant Pressure Mode.       1         Constant Pressure Mode.       1         Reverse Delay Time       1         Brake Delay Time       1         Brake Delay Time       1         Constant Pressure Mode.       1         Constant Pressure Mode.       1         Maintenance Alert Trigger       1         Mid-travel Stop Position       1         Matintalizate Enable.       1         Antenna Installation       1         Matio Transmitter Learn       1         MGT Obstacle Transmitter Learn       1         MGT Obstacle Transmitter Delete       1         MGT Obstacle Transmitter Delete

Reverse Loop
Operation Indications 22
Power-up Display 22
Idle Condition 22
Last Gate Position/Condition 22
Pre-start Delay
Reverse Delay
Run Timer
Error Indications
Entrapment
COMM LINK Connection Failure
MGT Obstacle Transmitter Trouble
Maximum Run Time Exceeded
How to Order Replacement Parts
Troubleshooting
Contacting Technical Support
Operator fails to start
Motor operates, but gate does not move
Motor sounds like it is working harder than normal
Limit switch getting out of time
Gate stopping part way open or closed
Gate staying open with automatic system
Preventative Maintenance
General
Lubrication
6-Month Preventative Maintenance
FCC Notice
Model VS-GSWG Exploded View
Controller Parts List
Variable Speed Drive Programming
Programming the Hitachi Inverter 20
Gate Arm Assembly Parts List
Gate Operator Installation Checklist



### **Pre-installation Information**

#### Before You Begin...

Before unpacking, inspect the carton for exterior damage. If you find damage, advise the delivery carrier of a potential claim. Inspect your package carefully. You can check your accessory box parts with the enclosed packing slip for your convenience. Claims for shortages will be honored for only 30 days from the date of shipment.

Before installing the operator, read this manual completely to ensure all requirements for proper installation are present. Verify that the voltage to be used matches the voltage of the operator.

If you have any questions about the requirements for proper installation of this gate operator contact technical support at 800-421-1587.

#### Always Check the Gate's Action

It's very important before installing the gate operator to make sure the gate's swing is free and level throughout the entire swing path. If the gate does not seem to operate properly, it may affect the operator performance or greatly shorten the life of the unit. The gate should also be designed so that airflow is ample to prevent wind resistance and drag.

#### **Gate Operator Classifications**

All gate operators can be divided into one of four different classifications, depending on their design and usage. Install this gate operator only when the operator is appropriate for the construction and usage class as defined below:

Class I Residential Vehicular Gate Operator
 A vehicular gate operator intended for use in a home or for one to four single family dwellings with a common garage or parking area

associated with these dwellings.

- Class II Commercial / General Access Vehicular Gate Operator
   A vehicular gate operator intended for use in a commercial location or
   building such as a multi-family housing unit of five or more single family
   units, hotel, retail store or other building servicing the general public.
- Class III Industrial / Limited Access Vehicular Gate Operator A vehicular gate operator intended for use in an industrial location or building such as a factory or loading dock area or other location not intended to service the general public.
- Class IV Restricted Access Vehicular Gate Operator A vehicular gate operator intended for use in a guarded industrial location or building such as an airport security area or other restricted access locations not servicing the general public, in which unauthorized access is prevented via supervision by security personnel.

#### **Approved Obstruction Detection Devices**

The following contact or non-contact obstruction detection devices have been approved for use with this swing gate operator as part of a UL325 compliant installation:

- Contact Edges Miller Edge Models MGO20, MGR20, MGS20, ME120
- Photoeyes MMTC Model IR-55 (165' range - P/N 2520-441) MMTC Model E3K (28' range - P/N 2520-031)

### Safety Information and Warnings

THE FOLLOWING FORMATS ARE USED FOR SAFETY NOTES IN THESE INSTRUCTIONS.



This type of warning note is used to indicate the possibility of damage to the gate or gate operator.

**A** WARNING **A** This type of warning note is used to indicate possible mechanical hazards that may cause serious injuries or death.

A WARNING A This type of warning note is used to indicate possible electrical shock hazards that may cause serious injuries or death.

#### **Regulatory Warnings**

Read the following before beginning to install this swing gate operator:

IMPORTANT INSTALLATION SAFETY INSTRUCTIONS

### TO REDUCE THE RISK OF SEVERE INJURY OR DEATH TO PERSONS, REVIEW THESE INSTALLATION SAFETY STEPS BEFORE PROCEEDING

- 1. READ AND FOLLOW ALL INSTALLATION INSTRUCTIONS.
- 2. Read the yellow "Safety Instructions" brochure enclosed with the packet of information. If any pages are missing or are unreadable, or you do not have the safety instructions, please call Linear at 1-800-421-1587 to request additional copies.
- 3. ALL ELECTRICAL CONNECTIONS TO THE POWER SUPPLY MUST BE MADE BY A LICENSED ELECTRICIAN AND MUST OBSERVE ALL NATIONAL AND LOCAL ELECTRICAL CODES.
- 4. A separate power-disconnect switch should be located near the operator so that primary power can be turned off when necessary.
- 5. Install the enclosed warning signs on both sides of the gate. A minimum of two (2) WARNING SIGNS shall be installed, one on each side of the gate where easily visible.
- 6. Never reach between, through or around the fence to operate the gate.
- 7. Never connect a button station within reach of the gate or on the side of the gate operator.
- 8. Do not adjust the operator controller's current sensing feature too high. It should be adjusted high enough to keep the gate from falsely triggering the sensing, but no higher than necessary for the gate to operate. DO NOT DEFEAT THE PURPOSE OF THIS FUNCTION!
- 9. You must install all required safety equipment.
- 10. UL325 Compliance requires the use of contact edges or photoelectric controls on all automatic or remotely-controlled gate operators.
- 11. The operator is intended for installation only on gates used for vehicles. Pedestrians must be supplied with a separate access opening. The pedestrian access opening shall be designed to promote pedestrian usage. Locate the gate such that persons will not come into contact with the vehicular gate during the entire path of travel of the vehicular gate.

### **Wiring Specifications**

Refer to the following steps for details on power and accessory wiring for the operator.

#### . WARNING 🕰

ALL AC ELECTRICAL CONNECTIONS TO THE POWER SOURCE AND THE OPERATOR MUST BE MADE BY A LICENSED ELECTRICIAN AND MUST OBSERVE ALL NATIONAL AND LOCAL ELECTRICAL CODES.

### **USE COPPER WIRE ONLY!**

#### **AC Power Wiring**

- 1. Find the listing on this page corresponding to the model, voltage and horsepower rating of your operator.
- 2. The distance shown in the table is measured in feet from the operator to the power source. DO NOT EXCEED THE MAXIMUM DISTANCE. These calculations have been based on standard 115 V and 230 V supplies with a 10% drop allowable. If your supply is under the standard rating, the runs listed may be longer than what your application will handle, and you should not run wire too near the maximum distance for the gauge of wire you are using.
- 3. When large-gauge wire is used, a separate junction box (not supplied) may be needed for the operator power connection.
- 4. Wire length calculations are based on the National Electrical Code, Article 430 and have been carefully determined based on motor inrush, brake solenoids, and operator requirements.
- 5. Connect power in accordance with local codes. The green ground wire must be properly connected.
- 6. Wire insulation must be suitable to the application.
- Electrical outlets are supplied in all 115 VAC models for convenience with occasional use or low power consumption devices only. If you choose to run dedicated equipment from these devices, it will decrease the distance for maximum length and the charts will no longer be accurate.

#### **DC Control and Accessory Wiring**

- 1. All control devices are now 24 VDC, which can be run up to 2000 feet with 14 AWG wire.
- Control wiring must be run in a separate conduit from power wiring. Running them together may cause interference and faulty signals in some accessories.
- A three-wire shielded conductor cable is required to connect two operators together for dual operation. You must use Belden 8760 Twisted Pair Shielded Cable (or equivalent) only – P/N 2500-1982, per foot). See Page 21 for details of this connection. Note: The shield wire should be connected in both the operators.

MODEL VS-GSWG SINGLE PHASE POWER WIRING				
	MAXIMUM DIS	TANCE (FEET)		
VULIS & TP	SINGLE	DUAL	WIKE GAUGE	
	222	111	12	
	354	177	10	
	566	283	8	
1/2-HP	900	450	6	
	1430	715	4	
	178	89	12	
	282	141	10	
	450	255	8	
3/4-HP	716	358	6	
	1140	570	4	
	160	80	12	
	254	127	10	
	406	203	8	
1-HP	646	323	6	
	1026	513	4	
	760	380	12	
	1200	600	10	
208 VOLIS	1924	962	8	
1/2-HP	3060	1830	6	
	4864	2432	4	
	604	302	12	
	958	478	10	
208 VOLIS	1526	763	8	
3/4-HP	2424	1212	6	
	3856	1928	4	
	544	272	12	
208 VOLTS 1-HP	864	432	10	
	1374	686	8	
	2184	1092	6	
	3476	1738	4	
	894	447	12	
2001/01/70	1422	711	10	
230 VOLIS	2264	1132	8	
1/2-HP	3600	1800	6	
	5724	2862	4	
	710	355	12	
2001/01/70	1128	564	10	
230 VOLIS	1706	207 208	8	
3/4-HP	2852	1/26	6	
	1538	2260	1	
	6/0	320	12	
	1016	508	10	
230 VOLTS	1616	808		
1-HP	2570	1085	6	
	4000	2045		
	4090	2040	4	

MODEL VS-GSWG THREE PHASE POWER WIRING				
VOLTS & HP	MAXIMUM DIS SINGLE	TANCE (FEET) DUAL	WIRE GAUGE	
208 VOLTS	1142	571	12	
1/2_HP	1816	908	10	
1/ <b>2-</b> 11F	2890	1445	8	
208 VOLTS	920	460	12	
3//_HP	1464	732	10	
5/4-11	2330	1165	8	
208 VOLTS	714	357	12	
1_HP	1136	568	10	
1-111	1804	902	8	
230 VOLTS	1344	672	12	
1/2-HP	2137	1069	10	
1/2-111	3400	1700	8	
230 VOLTS 3/4-HP	1084	542	12	
	1723	862	10	
0/+111	2741	1371	8	
230 VOLTS 1-HP	840	420	12	
	1336	668	10	
	2124	1062	8	
460 VOLTS	3841	1921	12	
1/2-HP	6106	3053	10	
1/2 1 11	9/12	4856	8	
460 VOLTS	3279	1640	12	
3/4-HP	5212	2606	10	
0/7111	8291	4146	8	
460 VOLTS	2689	1345	12	
1_HD	4274	2437	10	
I-HP	6709	3300	0	

### **Mounting Pad Installation**

The gate operator mounts bolted to posts secured in concrete footings. The posts support the operator and prevent it from moving during operation.

#### **Gate Preparation**

Before installing the gate operator, make sure the gate's swing is free and level throughout the entire swing path. If the gate does not seem to operate properly, it may affect the operator performance or greatly shorten the life of the unit. The gate should be designed so that airflow is ample to prevent wind resistance and drag.

#### **Mounting Specifications**

Use two 3 - 3-1/2" OD galvanized posts and secure with concrete footings as shown, length to be determined by local codes, frost line depth and soil conditions.

Attach the operator with the U-bolts, side plates and hardware provided. Four 3/16" side plates go on the outside top and bottom, two 3/16" side plates go on the inside top, and two 1/2" side plates go on the inside bottom (see the illustration at right). The operator should be positioned at a level to allow the arm to be installed at mid-height on the gate. "H" dimension can vary depending on gate construction. Make sure the posts do not protrude above the operator cabinet.

✓ **NOTE:** If non-standard mounting is necessary, consult the factory.

### 🏔 WARNING 🕰

The operator is intended for installation only on gates used for vehicles. Pedestrians must be supplied with a separate access opening. The pedestrian access opening shall be designed to promote pedestrian usage. Locate the gate such that persons will not come into contact with the vehicular gate during the entire path of travel of the vehicular gate.

### WARNING A

The gate must be installed in a location so that enough clearance is supplied between the gate and adjacent structures when opening and closing to reduce the risk of entrapment. Swing gates shall not open into public areas.



Figure 1. Side Plate Installation



Figure 2. Mounting Pad Specifications

### **Operator Preparation**

#### **Vent Plug Installation**

In order to keep gear oil from spilling out during shipping, gear reducers used in gate operators have either a solid plug, or a sealed vent plug, installed at the factory.

For operators with a solid plug, replace the solid plug with the vent plug provided (see Figure 3).

With the vent plug installed, remove the vent plug's breather pin to allow the gear box to vent (see Figure 3).

#### **Gate Arm Installation**

The gate arm connects the operator to the gate. The arm supplied can be used in left-hand or right-hand installations.

#### **Gate Arm Assembly**

Refer to Figure 4.

- 1. Remove the arm assembly cover.
- 2. Place the center hole in the rail guide over the 1" drive shaft.
- 3. Place the drive sprocket on drive shaft. Be sure the keyway is in place and set screws are secured.
- 4. Connect the gate bracket to the gate. Manually open the gate to approximately half-open position.
- 5. String the arm assembly chain as shown in Figure 4.
- ✓ NOTE: Observe the way the chain threads around the sprockets for left-hand or right-hand installations. Refer to Figure 4.
- 6. Adjust for taut chain tension but do not overtighten.
- 7. Replace the arm assembly cover.



Figure 3. Vent Plug Installation



Figure 4. Gate Arm Assembly

### **Operator Setup**

#### **Controller Access**

The Controller is protected by a plastic dust cover. To remove the dust cover, loosen the cover's wing-screw and lift the cover off (see Figure 5).

### A WARNING

l;

ALL AC ELECTRICAL CONNECTIONS TO THE POWER SOURCE AND THE OPERATOR MUST BE MADE BY A LICENSED ELECTRICIAN AND MUST OBSERVE ALL NATIONAL AND LOCAL ELECTRICAL CODES

#### **AC Power Connection**

All Linear gate operators are supplied with a power disconnect switch to turn on and off the power available to the operator. Following wiring specifications on Page 2, incoming power should be brought into the operator and connected to the labeled pigtails from the disconnect box. A wiring connections print can also be found on the label inside the cover of the operator.

Proper thermal protection is supplied with the operator. The motor contains a thermal overload protector to guard from overheating the motor due to overload or high-frequency operation. This overload protector will reset automatically after the motor cools down.

#### Earth Ground

Install a ground rod and connect it to the operator's frame in every gate operator installation. A good earth ground is necessary to allow the Controller's built-in surge and lightning protection circuitry to work effectively. The physical bolting of the operator to the mounting posts *is not* sufficient for a good earth ground.

- ✓ NOTE: Do not splice the ground wire. Use a single piece of solid copper 12 AWG wire between the ground rod and the operator.
- 1. Install an 8-foot long copper ground rod next to the operator mounting pad within three feet of the operator.
- 2. Use a clamp to connect a solid copper 12 AWG ground wire to the ground rod.
- 3. Route the ground wire to the operator.
- 4. Connect the ground wire to the operator's frame.



Figure 5. Controller Access



Figure 6. Power Disconnect Box Wiring

### **Operator Setup (cont.)**

### **Open and Close Limit Adjustment**

The limit nuts are not preset at the factory and must be adjusted for the gate in each installation. The limit switches are activated by two threaded nylon rotary limit nuts which are attached to a threaded limit shaft driven by a chain and sprockets from the main drive shaft. **REMOVE THE CARDBOARD FILLER BEFORE ADJUSTING THE LIMIT NUTS.** 

The Controller is factory setup for right-hand installations. The **OPEN** limit switches are the ones closer to the bottom of the operator. In left-hand installations, the **CLOSE** limit switches are the ones closer to the bottom of the operator (see Figures 7 & 8).

### CAUTION A

If the operator is installed in a left-hand installation. Set the Controller to left-hand operation BEFORE running the operator for the fine setting of the limit cams. Failure to do so will result in over-shooting the limit switches, and may cause damage to the operator and/or gate. Refer to programming on Page 12.

### Limit Nuts Rough Adjustment

Before running the operator, set the limit nuts as follows:

- 1. With the gate connected to the gate operator in a mid-travel position, turn the power disconnect switch **OFF**.
- 2. To adjust the limit nuts, press down on the detent plate and rotate the limit nut along the threaded shaft (see Figure 9).
- Adjust the OPEN limit nut until it is about 1/2" from activating the LSO-2 OPEN limit switch.
- Adjust the CLOSE limit nut until it is about 1/2" from activating the LSC-2 CLOSE limit switch.

### Limit Nuts Fine Adjustment

After finishing the rough limit nut adjustments, run the operator to set the fine limit adjustment.

- 1. Turn the power disconnect switch **ON**.
- 2. Stand clear of any moving parts and press the **OPEN** button.
- 3. After the gate opens, press the **CLOSE** button.
- 4. Observe the gate in both directions as it runs through each complete cycle. Adjust the open or close limit nuts again if necessary. Fine levels of adjustment can be made by adjusting a few teeth on the nut at a time. If the gate stops during travel, you may need to adjust the Open or Close Current Setting or the Maximum Run Timer (see Pages 13-14).

### Setting Speeds using LSO-2 & LSC-2

Limit switches LSO-2 and LSC-2 control when the operator accelerates to maximum speed and decelerates to minimum speed. It is recommended that LSO-2 and LSC-2 are adjusted first so the gate slows to near stop before hitting LSO-1 or LSC-1 as these will apply the brake upon activation.

Adjust LSO-2 and LSC-2 by slightly loosening the two screws which hold them in place and sliding toward or away from the center of the limit box. Care must be taken not to adjust too close to the center as the limit nut may travel past the switch and start accelerating at the end of the cycle.



Figure 7. Limit Box Assembly (Right-hand Installation)



Figure 8. Limit Box Assembly (Left-hand Installation)



Figure 9. Setting the Limits

#### **Torque Limiter Adjustment**

Before adjusting the torque limiter, make sure the gate is in good working condition. With the gate disconnected from the gate arm, one person should be able to move the gate by hand. Be certain the gate moves freely and without binding throughout its travel.

Torque limiters are set light at the factory. They must be adjusted during installation, preferably after limit cams have been manually set. With the gate arm and gate attached, adjust the torque limiter tight enough to keep it from slipping during normal operation. The inherent entrapment protection (current sensing) feature must activate prior to any slipping of the torque limiter.

✓ NOTE: The open and close current sensing may need to be adjusted before performing the following two steps. See Page 13.

#### To adjust the torque limiter in a Model VS-GSWG:

- 1. Loosen the set screw on the adjustment nut.
- Cycle the gate open and closed while observing the torque limiter action. TURN THE OPERATOR POWER DISCONNECT SWITCH OFF BEFORE MAKING ANY ADJUSTMENTS.

To *increase the torque*, turn the adjustment nut clockwise one flat, or 1/6 turn, at a time until desired output is obtained.

To *reduce the torque,* turn the adjustment nut counterclockwise one flat, or 1/6 turn, at a time until desired output is obtained.

3. When finished, tighten the set screw to lock the adjustment nut in place.



Figure 10. Model SWG Torque Limiter

### **Controller Features**



### **Indicator Descriptions**

INDICATOR DEFINITION		INDICATION WHEN LIT	INDICATION WHEN LIT	
OPERATION	PROGRAMMING	DURING NORMAL OPERATION	DURING PROGRAMMING	
24 VOLT INPUT POWER		LOW VOLTAGE AC POWER IS PRESENT		
24 VOLT DC ACCY POWER		LOW VOLTAGE DC POWER IS PRESENT		
OPEN		OPEN SIGNAL PRESENT FROM THE INTERNAL RECEIVER OR AN EXTERNAL DEVICE CONNECTED TO THE OPEN INPUT TERMINAL		
CLOSE		CLOSE SIGNAL IS PRESENT FROM A DEVICE CONNECTED TO THE CLOSE INPUT TERMINAL		
STOP		STOP INPUT TERMINAL IS OPEN AND NOT CONNECTED TO COMMON		
PROGRAM			CONTROLLER IS IN PROGRAMMING MODE	
REVERSE	DELAY SET	SIGNAL FROM REVERSING DEVICE IS PRESENT	SET REVERSE DELAY TIME	
LOCKOUT	ALARM SET	CONTROLS AND OPERATOR ARE LOCKED OUT BECAUSE OF EXISTING TROUBLE CONDITION	SET RUN ALARM AND PRE-START ALARM	
RADIO	LEARN	BUILT-IN RECEIVER IS DETECTING A RADIO SIGNAL FROM A REMOTE CONTROL	TRANSMITTERS CAN BE ENTERED INTO MEMORY (UP TO 40 TRANSMITTERS)	
OPEN CURRENT	SET	MOTOR CURRENT HAS EXCEEDED THE OPEN CURRENT SETTING WHILE OPENING	SET MAXIMUM OPEN CURRENT	
OPEN OBSTR	MGT 2 SET	OPEN OBSTRUCTION TERMINAL CONNECTED TO COMMON BY BEAM OR SAFETY EDGE, OR SIGNAL FROM MGT OBSTACLE TRANSMITTER	SET MGT #2 FUNCTION	
OPEN RELAY	LH/RH SET	OPEN RELAY IS ACTIVATED	SET LEFT-HAND RIGHT-HAND OPERATION	
OPEN LIMIT	BRAKE DELAY	OPEN LIMIT SWITCH IS ACTIVATED		
CLOSE CURRENT	SET	MOTOR CURRENT HAS EXCEEDED THE CLOSE CURRENT SETTING WHILE CLOSING	SET MAXIMUM CLOSE CURRENT	
CLOSE OBSTR	MGT 1 SET	CLOSE OBSTRUCTION TERMINAL CONNECTED TO COMMON BY BEAM OR SAFETY EDGE, OR SIGNAL FROM MGT OBSTACLE TRANSMITTER	SET MGT #1 FUNCTION	
CLOSE RELAY	AUTO CLOSE SET	CLOSE RELAY IS ACTIVATED	SET AUTO-CLOSE TIME	
CLOSE LIMIT	AC DC SET	CLOSE LIMIT SWITCH IS ACTIVATED	SET MOTOR TYPE	
SINGLE	SET	SINGLE TERMINAL CONNECTED TO COMMON BY AN EXTERNAL PUSHBUTTON OR RADIO		
MAX RUN	SET	MAXIMUM RUN TIMER HAS BEEN EXCEEDED	SET MAXIMUM RUN TIME	
COMM LINK	SET	DUAL OPERATOR CONNECTION DETECTED, BLINKS IF CONNECTION HAS FAILED		
MAINT ALERT	SET	MAINTENANCE IS REQUIRED ON OPERATOR	SET MAINTENANCE ALERT CYCLE COUNT	



### **Terminal Descriptions**

TERMINAL	GROUP	FUNCTION		
AC N		FACTORY CONNECTED TO 24 VAC FROM TRANSFORMER OR		
AC	24 VOLT INPUT	24 VDC FROM CONTINUOUS DUTY DC SUPPLY.		
DC -				
DC +	ACCESSONT TOWER	THOUDES 24 VOLT BUT OWENT ON ADDESSONIES. (.SA WIAK)		
RESET	BESET BUITTON	FACTORY CONNECTED TO THE CONTROLLER'S RESET BUTTON		
COMMON	HEGET BOTTON			
С				
В	COMM LINK	FOR 3-WIRE NETWORK CONNECTION TO SECOND OPERATOR IN DUAL GATE INSTALLATIONS.		
A				
COMMON	SINGLE BUTTON INPUT	CONNECT TO NORMALLY OPEN SWITCH FOR SINGLE BUTTON OPERATION. ALTERNATES		
SINGLE		BETWEEN OPEN-CLOSE OR OPEN-STOP-CLOSE DEPENDING ON PROGRAMMING.		
	FIRE BOX INPUT	CONNECT TO NORMALLY OPEN SWITCH IN FIRE BOX FOR FIRE DEPARTMENT ACCESS.		
FIRE DEPT	l			
COMMON		CONNECT TO NORMALLY OPEN DEVICES (KEYPAD, GARD READER, KEYSWITCH, TELEDHONE ENTRY SYSTEM) TO ODEN THE GATE A CONSTANT ODEN INDUIT WILL		
OPEN		OVERRIDE THE MID-TRAVEL STOP AND HALT THE AUTO CLOSE TIMER UNTIL RELEASED.		
OPEN	Î			
CLOSE	3-BUTTON	CONNECT TO 3-BUTTON STATION FOR OPEN-CLOSE-STOP CONTROL. A CONSTANT OPEN INPUT		
COMMON	STATION INPUT	WILL OVERRIDE THE MID-TRAVEL STOP AND HALT THE AUTO CLOSE TIMER UNTIL RELEASED.		
STOP				
СОМ	OPEN OBSTRUCTION	CONNECT TO NORMALLY OPEN DEVICES (GATE EDGE, PHOTO BEAM) TO DETECT AN OBSTRUCTION DURING OPENING. WHILE GATE IS MOVING, ANY OPEN OBSTRUCTION SIGNAL WILL CAUSE THE GATE TO STOP, REVERSE A SHORT DISTANCE, AND THEN STOP AGAIN, AT THIS TIME THE AUTO CLOSE TIMER IS DISABLED. AND A RENEWED INPUT		
O-OBS	INPUT	WILL BE REQUIRED TO START THE GATE AGAIN. SHOULD THE GATE BE RESTARTED AND THE OBSTACLE SIGNAL OCCUR AGAIN PRIOR TO REACHING A LIMIT, THE GATE WILL STOP AGAIN, LOCKOUT, AND SOUND THE CONTINUOUS TONE ALARM.		
C-OBS		CONNECT TO NORMALLY OPEN DEVICES (GATE EDGE, PHOTO BEAM) TO DETECT AN OBSTRUCTION DURING CLOSING. WHILE GATE IS MOVING, ANY CLOSE OBSTRUCTION SIGNAL WILL CAUSE THE GATE TO STOP, THEN REVERSE AND TRAVEL TO THE FULL OPEN POSITION. SHOULD A OPEN OBSTRUCTION INPUT OR AN OPEN DIRECTION		
СОМ	INPUT	INHERENT ENTRAPMENT CONDITION OCCUR PRIOR TO THE GATE REACHING THE OPEN LIMIT, THE OPERATOR WILL LOCKOUT AND SOUND THE CONTINUOUS TONE ALARM. IF THE AUTO CLOSE TIMER IS SET, WHEN THE CLOSE OBSTRUCTION INPUT IS CLEARED, THE GATE WILL CLOSE WHEN THE AUTO CLOSE TIMER EXPIRES.		
COM REV	REVERSE	CONNECT TO NORMALLY OPEN DEVICES TO CAUSE A REVERSAL WHEN THE GATE IS TRAVELING CLOSED. THE GATE WILL REVERSE TO THE FULL OPEN POSITION.		
OPEN LOOP	ĺ	CONNECT TO OPEN LOOP/FREE EXIT LOOP. THE GATE WILL OPEN		
OPEN LOOP	OPEN LOOP	WHEN THE LOOP IS TRIGGERED, AND REMAIN OPEN AS LONG AS THE LOOP IS TRIGGERED. REQUIRES LOOP DETECTOR.		
REVERSE LOOP		CONNECT TO REVERSE LOOP. TRIGGERING THE LOOP WILL CAUSE A		
REVERSE LOOP	REVERSE LOOP	REVERSAL WHEN THE GATE IS TRAVELING CLOSED. THE GATE WILL REVERSE TO THE FULL OPEN POSITION. REQUIRES LOOP DETECTOR.		
SHADOW/RESET LOOP		CONNECT TO SHADOW/RESET LOOP TO KEEP THE GATE IN ITS FULLY OPEN		
SHADOW/RESET LOOP	SHADOW/RESET LOOP	POSITION AS LONG AS THE SIGNAL IS PRESENT. USED TO KEEP GATE OPEN WHILE VEHICLE IS PASSING THROUGH. REQUIRES LOOP DETECTOR.		
- +	ALARM	FACTORY CONNECTED TO THE ALARM BEEPER.		
N.O.				
СОМ	AUX RELAY	FOR CONNECTION TO AUXILIARY DEVICES (MAGNETIC LOCK, SOLENOID LOCK,		
N.C.	1	STRUBE LIGHT) FOR ACTIVATION (OR DEACTIVATION) DURING GATE OPERATION.		
+				
-	24 VOLI SOLAR PANEL	NOT USED WITH THIS MODEL OPERATOR.		
+				
-	24 VOLI BALLERY	NUT USED WITH THIS MODEL OPERATOR.		

### **Operator Accessory Connections**



Figure 12. Operator Accessory Connections

### **Basic Controller Programming**

#### **Programming Overview**

The Controller can be programmed with various options for the operator. The programming fields are defined as "functions" that have "options". To make setup easier for the installer, the Controller's programming is divided into two groups: basic and advanced. The basic programming group contains the functions commonly used in most swing gate installations. The advanced programming group contains functions less commonly used (i.e. dual gate stagger delay, maximum run timer, etc.).

#### **Entering Programming Mode**

Enter programming mode by pressing the **UP** and **DOWN** buttons together for one second. While in programming mode the **PROGRAM** indicator will light.

#### **Exiting Programming Mode**

Exit programming mode at any time by pressing the **UP** and **DOWN** buttons together. The Controller will automatically exit programming mode after three minutes of inactivity.

#### **Programming Keystrokes**

#### (Typical Programming Method)

While in programming mode, press the **UP** or **DOWN** buttons to scroll through the programming functions. When the desired function is displayed press the **ENTER** button to display the currently set option for the function. When an option is displayed, the decimal points are lit.

To change the option, press and hold the **ENTER** button for 1 second. To indicate that an option is ready to be changed, the display will flash. While the display is flashing, press the **UP** or **DOWN** button to display the other options available for that function.

When the desired option is displayed, press the **ENTER** button to store it into memory. To select another function, press **ENTER**, **UP**, or **DOWN**.

#### Left or Right Hand Operation

The factory default is for right hand operation (operator on right side of the driveway when viewed from the inside of the gate). For left hand installations, program the Controller for left hand operation.

#### **Dual Gate Enable**

The factory default is for single gate operation. For dual gate operation, wire the two gate controllers together through the **COMM LINK** terminals (see Page 21) and enable dual gate operation with this programming step.

✓ NOTE: The Mid-travel Stop feature is disabled when dual gate operation is enabled for paired units.

#### Auto Close Timer

The factory default turns off the Auto Close Timer. The timer can be set from 1 to 59 seconds and from 1 to 9 minutes. When the Auto Close Timer is set, after opening, the gate will wait for the length of the Auto Close Timer then close automatically.











#### **Run Alarm and Pre-start Alarm**

The factory default is Run Alarm on and a 3-second Pre-start Alarm. The operator's beeper will sound 3 seconds before the operator starts. The options are:

- Run Alarm Off and Pre-start Alarm Off
- Run Alarm On and Pre-start Alarm Off
- Run Alarm On and Pre-start Alarm On for 1-9 Seconds

#### Maximum Open Direction Current Setting

To detect obstacles or mechanical problems with the gate, the operator monitors its motor current. If the open current load exceeds the programmed maximum load range number, the operator will stop, reverse a short distance, then stop again. The Auto Close Timer will be disabled, and another open request will be required to start the operator again. If after restart, the overload or an open obstacle happens again before the open limit is reached, the operator will lockout and sound the alarm.

To measure the motor load used during opening, *while this function is being displayed*, push and hold the **OPEN** button to fully open the gate. During movement, the motor current will be displayed as a load number from 0 to 99. This number is useful for troubleshooting but not for setting the motor current. At the end of travel, a different number will flash. This number indicates the range above and below the average motor current during the run. Using the + and - buttons, set the programmed range number so that a minimal force (50-75 lbs.) will activate a reversal should an obstruction occur, but high enough to keep the gate moving under normal conditions without interruption.

#### Maximum Close Direction Current Setting

To detect obstacles or mechanical problems with the gate, the operator monitors its motor current. If the close current load exceeds the programmed maximum load range number, the operator will stop, reverse, and travel to the full open position. Should a open obstruction input or an open direction inherent entrapment condition occur prior to the gate reaching the open limit, the operator will lockout and sound the continuous tone alarm. Another close request will be required to start the operator again. If after restart, the overload or a close obstacle happens again before the close limit is reached, the operator will lockout and sound the alarm. If the auto close timer is set, when the close obstruction input is cleared, the gate will close when the auto close timer expires.

To measure the motor load used during closing, *while this function is being displayed*, push and hold the **CLOSE** button to close the gate. During movement, the motor current will be displayed as a load number from 0 to 99. This number is useful for troubleshooting but not used for setting the motor current. At the end of travel, a different number will flash. This number indicates the range above and below the average motor current during the run. Using the + and - buttons, set the programmed range number so that a minimal force (50-75 lbs.) will activate a reversal should an obstruction occur, but high enough to keep the gate moving under normal conditions without interruption.







### Advanced Controller Programming

### **Entering Advanced Programming Mode**

To access and program the Advanced Programming functions, for each programming session, Advanced Programming must be enabled.

After exiting programming, the Advanced Programming functions will be available on the programming display during the next programming session unless the operator has run 50 or more cycles. After that, Advanced Programming must be enabled again.

### Maximum Run Time

The factory default for the Maximum Run Time (MRT) is 99 seconds. When the operator starts, a timer will begin counting. If a open or close limit is not reached or an obstacle or reversing input is not received before the timer expires, the operator will stop, the unit locks out and the alarm sounds. The timer can be set for 10 to 99 seconds, but should be left at 99 in most applications. Setting it too close to the actual run time may cause the time to expire with changing ambient temperature, gate conditions, etc...

If AC is present and an open or close limit is not reached or an obstacle or reversing input is not received before this timer exceeds MRT, the operator will stop, the unit locks out and the alarm sounds.

### Single Button Input Setup

This function is used for selecting the operation for single button controls and radio receivers.

The factory default sets the **SINGLE** input terminal so successive inputs will cycle the operator in OPEN-STOP-CLOSE-STOP order.

Alternately, the **SINGLE** input can be set to cause the gate to OPEN unless the gate is fully open. If the gate is fully open, the input will cause the gate to CLOSE.

### Stagger Mode

This function is used in dual gate installations only. The factory default sets the Stagger Mode to OFF. In dual gate installations the two operators communicate through the 3-wire **COMM LINK** interface. When using the Stagger Mode, set one operator for delayed opening and the other operator for delayed closing. The Stagger Time programming function (see below) sets the length of the delay.

✓ NOTE: This function will only be displayed if dual gate operation is selected.

### Stagger Delay Time

This function is used in dual gate installations only. The factory default sets the Stagger Time to 0 seconds (OFF). The Stagger Time sets the delay for the Stagger Mode. The Stagger Delay Time can be set from 1-99 seconds.

✓ NOTE: This function will only be displayed if dual gate operation is selected.











### **Advanced Controller Programming (Cont.)**

#### **Auxiliary Relay Mode**

The Auxiliary Relay has normally open and normally closed contacts. The factory setting disables the Auxiliary Relay. The relay can be set for:

- Maglock: To deactivate a magnetic or solenoid gate lock, the relay will energize during any pending or actual gate motion (open only).
- **M4:** To deactivate a magnetic or solenoid gate lock, the relay will energize during any pending or actual gate motion (open only). 3 seconds after the gate starts to move, the relay will de-energize. This option is used for higher current solenoid locks.
- **Ticket Dispenser:** The relay will energize while the gate is moving in the open direction and at the full open limit, or in an entrapment condition.
- **Strobe:** To activate a warning strobe light, the relay will energize during any pending or actual gate motion (either open or close).
- Alarm: The relay will energize if the gate is manually forced open from the full closed position.

#### **Reverse Delay Time**

The factory default sets the Reverse Delay to 1 second. The operator will wait the length of the delay before reversing direction. This feature will not change the reversal time when the operator is responding to an entrapment condition from an obstruction input or inherent entrapment protection sensor. The Reverse Delay can be set from 1 to 9 seconds. Heaver gates require a longer delay to allow time for the gate to stop.

#### Brake Delay Time

This function is displayed, but only used in operators with mechanical brakes. The Model VS-GSWG does not have a mechanical brake.

The factory default sets the Brake Delay to no delay (0 seconds). Heavy gates may require delayed braking to allow the gate to slow down before stopping it. The operator can be set to wait the length of the delay after running before applying the brake. The Brake Delay can be set from 0 to 3 seconds.

#### **Constant Pressure Mode**

The factory default allows momentary pressure on a control station's **OPEN** or **CLOSE** button to cycle the operator. The controller can be set to require constant pressure on the **OPEN**, **CLOSE**, or both buttons to run the operator.

✓ NOTE: If a button is set for constant pressure, and it is released before the operator reaches the open or close limit, the operator will stop the gate at its current position.

#### Shadow Loop Open Prevention

If the shadow loop is triggered, it always prevents the gate from *closing* if the Auto Close Timer activates or a CLOSE command is given while the gate is at the full open position.

The controller can also be set to prevent the gate from *opening* if the shadow loop is triggered while the gate is at the close limit position. This prevents a swing gate from opening into a vehicle if it's parked near the gate on the inside.





### **Advanced Controller Programming (Cont.)**

#### **Reset Cycle Count**

The Controller counts of the number of times the operator has been cycled full open and close. The cycle count can be displayed. The display will scroll the cycle count number, flashing two digits at a time from left to right.

To reset the Cycle Count, press and hold the **ENTER** button for 2 seconds while the Cycle Count is displayed.

If the Maintenance Alert has been triggered, resetting the Cycle Count will also reset the Maintenance Alert indicator.

#### Maintenance Alert Trigger

The Controller has a **MAINT ALERT** indicator that can be programmed to light when the number of activations exceeds a set number of cycles.

The factory default sets the Maintenance Alert Trigger to 10,000 cycles. The Maintenance Alert Trigger can be programmed for 5, 10, 15, or 25 thousand cycles.

The Maintenance Cycle Count can be reset independently from the operator's absolute Cycle Count.

#### **Mid-travel Stop Position**

The Controller can be programmed so the gate will stop at a mid-travel point instead of fully opening. This can be useful in installations where a large gate, that takes a long time to open and close fully, only needs to be opened partway to allow traffic to pass.

The factory default sets the Controller for full open operation. Alternately, the Controller can be programmed to open for 1 to 99 seconds then stop, before reaching the open limit.

When a Mid-travel Stop Position time has been programmed, the gate will **still fully open** if the Fire Department input is triggered, if the **OPEN** button is held down beyond the Mid-travel Stop Position, or a close obstruction or reverse loop input is triggered.

✓ NOTE: The Mid-travel Stop feature is disabled when dual gate operation is enabled for paired units.

#### Anti-tailgate Enable

The factory default sets the Anti-tailgate Enable to OFF. With this setting, during a gate cycle, after the shadow loop has been triggered by the vehicle and then has cleared after the vehicle passes, the Auto Close Timer or a CLOSE command is required to begin closing the gate.

If the Anti-tailgate Enable is set to ON, the gate will close immediately as soon as the shadow loop has cleared. Any subsequent shadow loop triggers while the gate is closing will stop the gate. When the shadow loop clears, the gate will continue closing.

#### Radio Enable

The Controller contains a built-in MegaCode® radio receiver to allow activation from up to 40 access control transmitters and two Model MGT (gate edge) transmitters. The factory default enables the internal radio receiver. Alternately, the internal receiver can be disabled.

#### Antenna Installation

The Controller is supplied with a local whip antenna installed. If using a remote antenna, remove the whip antenna and connect coax cable from the antenna to the **ANTENNA** connector.











### **Advanced Controller Programming (Cont.)**

#### Radio Transmitter Learn

The Controller's built-in MegaCode® radio receiver can store the IDs of up to 40 transmitters. Refer to the figure for the steps required to learn transmitters.

✓ NOTE: This function will NOT be displayed if the transmitter memory is full, or if the radio receiver is disabled.

#### **Radio Transmitter Delete**

Transmitters can be deleted from the Controller's memory either individually, or all at the same time. Refer to the figure for the steps required to delete transmitters.

✓ NOTE: This function will NOT be displayed if no transmitters are stored in memory, or if the radio receiver is disabled.

#### MGT Obstacle Transmitter Learn

The Controller supports one or two Model MGT Obstacle Transmitters. The transmitters can be programmed to function as Open Obstruction, Close Obstruction, Reverse, or Stop. Refer to the figure for the steps required to learn MGT transmitters.

✓ NOTE: This function will NOT be displayed if two MGT transmitters are already stored in memory, or if the radio receiver is disabled.

#### MGT Obstacle Transmitter Delete

MGT transmitters can be deleted from the Controller's memory either individually, or all at the same time. Refer to the figure for the steps required to delete MGT transmitters.

✓ NOTE: This function will NOT be displayed if no MGT transmitters are stored in memory, or if the radio receiver is disabled.

#### **Motor Type Selection**

The factory sets the default for the Controller to match the type of motor in the operator. If required, change the motor selection option to a different type of motor used in the operator. The options available are:

- AC Motor Only
- DC Motor Only with Mechanical Braking
- DC Motor with Electronic Soft Start/Stop
- 3 Phase AC Motor
- AC Motor with DC Motor Backup with Mechanical Braking
- AC Motor with DC Motor Backup with Electronic Soft Start/Stop

#### **Reset Controller to Factory Defaults**

The Controller can be reset with this function. **ALL PROGRAMMED DATA WILL BE LOST**, and the factory defaults will be loaded. This function will not erase radio transmitters, current sense values, or motor type. Transmitters must be deleted with the two functions above.









DELETE

TRANSMITTERS





### **Loop Layout Illustration**





### **Photoeye Installation Illustration**



### **Dual Gate Installations**

Two operators can be used in dual gate installations. The operators communicate with each other through the 3-wire **COMM LINK** terminals.

When one operator activates, the **COMM LINK** connection signals the other operator to activate. Each operator functions independently, controlling its gate and monitoring its inputs and accessories.

A three-wire shielded conductor cable is required to connect two operators together for dual operation. Use Belden 8760 Twisted Pair Shielded Cable (or equivalent) only - P/N 2500-1982, per foot).

✓ NOTE: The shield wire should be connected COMM LINK terminal "C" in both operators.

Three of the programming functions available are only used for dual gate installations:

• Dual Gate Enable

Dual Gate Enable must be set for all dual gate installations.

• Stagger Mode

The Stagger Mode function determines if the operator has a delayed open or a delayed close. In dual swing gate installations, typically one operator is programmed for delayed open, and the other operator is programmed for delayed close.

#### • Stagger Delay Time

The Stagger Time sets the length of the delay for the Stagger Mode.

See Pages 12 & 14 for details on these three dual gate programming functions.

Set the following parameters in each gate operator individually in a single gate mode before connecting the network cable and operating in dual gate mode.

- 1. Open and Close Limit settings
- 2. Open and Closed direction inherent entrapment protection (OC & CC)

After these parameters have been set, and each operator has been tested independently and is functioning correctly in single gate mode, then set BOTH operators to dual gate (dg) in the Paired Mode setup step under Basic Programming steps.



### package that includes an in-cabinet heater to keep the drive train and electronics warm in cold environments.

**Optional In-Cabinet Heater** 

In-cabinet heaters can also be ordered separately and should be wired to the operator as shown in Figure 14 Contact Technical Services for heater wiring information for a specific voltage and phase of operator.

The operator can be ordered with an optional cold weather



Figure 14. In-cabinet Heater Wiring

### **Gate Operation**

#### **Open Button**

Opens the gate. If the Controller is programmed to stop opening the gate at mid-travel, a constant press of the **OPEN** button will override the Mid-travel Stop and completely open the gate. If the Auto Close Timer is set, it will be suspended until the **OPEN** button is released.

#### **Close Button**

Closes the gate if the gate is open. Also closes the gate if the gate is in the process of opening.

#### Stop Button

Stops the gate from opening or closing at any time.

#### Single Input

Opens the gate if it's closed and closes the gate if it's open (open-close programming option). Activating the input while the gate is moving will reverse the gate.

Can be programmed to stop the gate while the gate is moving (open-stop-close programming option).

#### Fire Department Input

Fully opens the gate when the input is activated. Overrides the Mid-travel Stop and Auto Close Timer (if either is programmed for the gate). The gate will lockout in the open position without sounding the alarm. Press the **STOP** button to release the lockout.

#### **Open Input**

Functions the same as the **OPEN** button.

#### **Open Obstruction**

While the gate is opening, any open obstruction signal will cause the gate to stop, reverse a short distance, and then stop again. The Auto Close Timer will be disabled, and a renewed input will be required to start the gate again. Should the gate be restarted and the obstacle signal occur again prior to reaching a limit, the gate will stop again, lockout, and sound the emergency alarm.

#### **Close Obstruction**

While the gate is closing, any close obstruction signal will cause the gate to stop, reverse, and travel to the full open position. Should a open obstruction input or an open direction inherent entrapment condition occur prior to the gate reaching the open limit, the operator will lockout and sound the continuous tone alarm. Another close request will be required to start the operator again. If after restart, the overload or a close obstacle happens again before the close limit is reached, the operator will lockout and sound the alarm. If the auto close timer is set, when the close obstruction input is cleared, the gate will close when the auto close timer expires.

#### **Reverse Input**

If the reverse input is triggered while the gate is closing, the gate will reverse to the full open position. If the Auto Close Timer is set, when the reverse input is cleared, the gate will close when the Auto Close Timer expires.

#### **Open Loop**

Functions the same as the **OPEN** button.

#### **Reverse Loop**

Functions the same as the reverse input.

#### Shadow/Reset Loop

Holds the gate fully open or fully closed while triggered. If open, the gate closes immediately when cleared if Anti-tailgate is enabled.

#### **Operation Indications**

During normal operation, the Controller's displays will indicate current operating conditions and status.

#### **Power-up Display**

When the Controller powers up, dashes will show on the display, then the firmware version number, then the gate type (SL for slide and swing gates).

Exiting programming restarts the Controller. The power-up display will show upon the restart.

#### **Idle Condition**

While the Controller is idling, waiting for a command, the display will show circulating dashes.

#### Last Gate Position/Condition

When the gate moves or stops, the display will show the status for up to one minute.

- Stop is displayed as 5E
- Full Close is displayed as FE
- Full Open is displayed as FD
- Entrapment is displayed as En

#### **Pre-start Delay**

During the pre-start delay, the display will countdown the number of seconds remaining before the operator starts.

#### **Reverse Delay**

If the gate travel direction is reversed from a user activation or reversing device, and a reverse delay is set, the display will count down the delay time in seconds before the operator restarts.

#### Run Timer

While the gate is opening or closing, the number of seconds running time is displayed.

### **Error Indications**

During abnormal operation, the Controller's displays and beeper will indicate the error condition that has occurred.

#### Entrapment

If an entrapment condition occurs detected by two repeated open or close obstruction triggers, the Controller will lock the operator out. The beeper will sound constantly and the gate will not operate. To reset the Controller press the **STOP** button or press the **RESET** button on the operator's cover.

### WARNING A

The Stop and/or Reset button must be located in the line-ofsight of the gate. Activation of the reset control shall not cause the operator to start.

#### **COMM LINK Connection Failure**

In dual gate installations, if there is a connection failure between the two operators, the **COMM LINK** indicator will blink once a second. During this condition the gate will not operate, except if triggered by the **FIRE DEPT** input, which functions normally.

#### MGT Obstacle Transmitter Trouble

If any MGT transmitters are used with the operator, their supervision feature will alert the Controller if there is any trouble with the transmitter. MGT transmitters send hourly status reports and will send low battery reports when the transmitter has a low battery. The MGT transmitters also have a tamper detection switch that will trigger when their case is opened.

When the Controller detects a low transmitter battery, a tamper signal, or missing transmitter status reports, the gate will still operate normally, but the beeper will change as follows:

- The Pre-start Alarm will beep twice as fast.
- The Run Alarm will beep twice as fast and continue for five minutes after the gate stops.
- The sounder will "chirp" every five seconds when the gate is idle.

Correct the trouble (close case, replace battery, or replace transmitter) to clear the obstacle transmitter trouble indications.

#### Maximum Run Time Exceeded

If the Maximum Run Time is exceeded, the Controller stops the operator the same as if a double obstacle has occurred in an entrapment condition. The entrapment alarm sounds constantly, and is cleared by pressing the **STOP** button or the **RESET** button on the cover. After the **STOP** or **RESET** button is pressed, because the Maximum Run Time has been exceeded, the sounder will beep twice every five seconds. The next operation of the gate will clear the indication.

CONTROLLER ERROR CAUSES AND INDICATIONS				
ERROR CAUSE	ERROR INDICATION	HOW TO CLEAR		
TWO SAFETY REVERSALS (ON SINGLE GATE OR ON EITHER DUAL GATE)	En DD, CONTINUOUS ALARM BEEPER, GATE DISABLED	PRESS STOP BUTTON		
MAXIMUM RUN TIMER EXCEEDED ON OPENING	En D I, AND MAX RUN LED, CONTINUOUS ALARM BEEPER, GATE DISABLED	PRESS STOP BUTTON, CLEARS CONTINUOUS ALARM, THEN DOUBLE BEEP EVERY 5 SECONDS UNTIL NEXT OPERATION		
MAXIMUM RUN TIMER EXCEEDED ON CLOSING	En 02, AND MAX RUN LED, CONTINUOUS ALARM BEEPER, GATE DISABLED	PRESS STOP BUTTON, CLEARS CONTINUOUS ALARM, THEN DOUBLE BEEP EVERY 5 SECONDS UNTIL NEXT OPERATION		
COMM LINK FAILURE	En D3, AND COMM LINK LED, CONTINUOUS ALARM BEEPER FOR 1 MINUTE, GATE DISABLED (EXCEPT FOR FIRE DEPT INPUT)	PRESS STOP BUTTON, CLEARS CONTINUOUS ALARM		
GATE FULL OPEN RESULTING FROM FIRE DEPT INPUT	En DH, GATE DISABLED	PRESS STOP BUTTON		
FAIL SAFE OR FAIL SECURE BECAUSE OF BATTERY VOLTAGE DROP BELOW 21.6 VDC DUE TO AC POWER LOSS	En 05, GATE DISABLED	BATTERY VOLTAGE MUST RISE ABOVE 24 VDC		
OTHER CONTROLLER IN ENTRAPMENT (DUAL GATE)	En 06, GATE DISABLED	CLEAR ENTRAPMENT ON OTHER CONTROLLER (PRESS STOP)		
LOW AC VOLTAGE AT CONTROLLER	En DT, GATE DISABLED	RESTORE AC POWER TO NORMAL LEVEL		
INPUT TRIGGERED DURING ENTRAPMENT LOCKOUT	En 08, GATE DISABLED	PRESS STOP BUTTON		
COMPATIBILITY PROBLEM	En 09, GATE DISABLED	UPDATE FIRMWARE AND RESET BOTH PAIRED CONTROLLERS		
EEPROM PROBLEM	En ID. GATE DISABLED	TRY RESET, CALL TECH, SUPPORT		
DC MOTOR MISMATCH	En 11, GATE DISABLED	REPROGRAM MOTOR TYPE OR CHANGE DC MOTOR BOARD, NEXT GATE MOVEMENT WILL RETRY DC MOTOR CHECK		
MOTOR FAILURE	En 12, GATE DISABLED	CALL TECH. SUPPORT		
AC POWER LOSS IN OPEN OR CLOSE IMMEDIATE POWER FAIL MODE	En 13	REAPPLY AC POWER		
MAXIMUM RUN TIMER EXCEEDED AFTER AC POWER LOSS	En H	BATTERY VOLTAGE MUST RISE ABOVE 24 VOLTS		
MGT SUPERVISORY CONDITION (TAMPER, LOW BATTERY,	FAST BEEPS DURING PRESTART, FAST BEEP RUN ALARM, CHIRP	CLEARS WHEN MGT CONDITION CLEARS		

#### Troubleshooting

#### **Contacting Technical Support**

For technical questions regarding Linear gate operators, contact the Technical Services Department at:

#### 1-800-421-1587 from 5:00 AM to 4:30 PM Pacific time

#### **Operator fails to start**

- A. If the operator has been running a large number of cycles, the motor may have become too hot and tripped its thermal overload breaker. Allow the motor to cool down and the thermal overload breaker will reset automatically.
- B. Make sure you have power at the master distribution panel and that the power has not been turned off.

#### Motor operates, but gate does not move

- A. In operators with torque limiters and friction pad clutches, check for signs of slipping. You can mark the sprocket and clutch with a yellow or white grease pen and watch for the lines to move apart if slipping is taking place. Adjust the torque limiter tighter if this is the problem.
- B. Check for broken chain or worn belts.
- C. Check all setscrews on pulleys and sprockets and tighten them if necessary, and check for keys which may have fallen loose from keyways.

#### Motor sounds like it is working harder than normal

- A. Make sure the gate is moving freely and without binding throughout its entire travel.
- B. Check the drive chain for obstructions (if the operator has one).
- C. If the operator has an internal brake mechanism, make sure it is releasing.

#### *Limit switch getting out of time*

A. Check the setscrews in limit cams for tightness. Replace if necessary.

## *Gate stopping part way open or closed (but no visible obstruction)*

- A. The Controller may have received a false obstruction input triggered by current sensing set too low. Make sure the gate moves freely through its entire travel before adjusting the current sensing.
- B. The Maximum Run Timer may have counted down and expired. This can be caused by having the timer set too low, if a chain or belt is broken, or if a sprocket or pulley is slipping. When the timer expires, the gate stops and the beeper will sound.
- C. An obstruction signal from an accessory wired to the obstruction input may have triggered falsely. Check the control board for lit indicators for any of the following inputs: safety, shadow/reset, open obstruction, close obstruction, stop, etc. If any are lit when the operator should be running, remove all devices hooked to that function and hook them up one at a time and try to run the operator until the problem device is found. Refer to Page 9 for details on the control board indicators.

#### Gate staying open with automatic system

- A. If there are vehicle detectors used with the operator, one of the loops or loop detectors may be sending a false signal or needs to be reset. Observe the indicators on the loop detector. Unplug the detector and try running the operator.
- B. An opening or reversing device may be stuck or malfunctioning. Try disconnecting these devices and hook them back up one at a time and try running the operator until the malfunctioning device is found.
- C. Make sure the close limit switch isn't activated. If it is, the operator will think the gate is already closed.

#### How to Order Replacement Parts

Use the part numbers listed on the following pages.

Contact your local Linear dealer or distributor to order parts.

- 1. Supply the model number and serial number of your operator.
- 2. Specify the quantity of pieces needed and order by part number and name of part.
- 3. State whether to ship by freight, truck, parcel post, UPS or air express.
- 4. State whether transportation charges are to be prepaid or collect.
- 5. Specify name and address of person or company to whom parts are to be shipped.
- 6. Specify name and address of person or company to whom invoice is to be sent.

### **Preventative Maintenance**

### WARNING **A**

Always disconnect power from operator before servicing. Keep clear of gate during operation.

#### General

Linear gate operators are designed for many years of trouble-free operation and, under recommended operating conditions, will require only minimal maintenance. To ensure that a unit is ready for operation at all times, and to preclude serious damage or failure, inspect the unit systematically. Proper adjustments and lubrication should be made as recommended.

#### **Lubrication**

- ✓ Bearings For models which have pillow block style bearings with grease fittings, lubricate at least twice a year with a lithium complex based, petroleum oil NLGI 2 rated grease. Oilite and precision sealed bearings do not require additional lubrication.
- ✓ Motor Motors have sealed ball bearings and do not require further lubrication. If bearing noise develops after several years of operation, bearings should be replaced by a motor repair company, or the motor should be replaced if necessary.
- ✓ Swing Gate Arm Check all bolts for proper tension and tighten if necessary. Lightly lubricate all pivot points with a light machine oil.

For all gate operators, you must inspect the gate for proper operation. The gate should move easily without binding through its entire travel. If the gate does bind, adjust or fix as required. Failure to keep the gate in good working condition will have adverse effects on the operator.

#### 6-Month Preventative Maintenance

- 1. For operators which utilize torque limiting clutches, check for proper tightness. If there appears to be dust from wear on the pads, inspect the pads and replace if necessary. If the clutch cannot be adjusted tightly enough to move the gate without slipping, the pads must be replaced.
- 2. For operators with V-belts, inspect for wear and replace as necessary. Check for proper tension and adjust if required. Check all pulley setscrews for tightness and tighten if necessary.
- 3. For operators with internal chain drives, inspect chain and sprockets for wear and replace if necessary. Check for proper tension and alignment, and adjust if required. Check all hub sprocket setscrews and tighten if required.
- 4. Check limit switches and limit actuators (cams, limit nuts, etc.) for wear and replace as required. In rotary limit switch assemblies, wipe the limit shaft clean and apply a light coating of dry lubricant.
- 5. For operators with magnetic brakes, check for proper adjustment. Brake disc must run free when the brake is engaged. For brake assemblies other than C-face style, the brake should be adjusted so that the solenoid plunger throw is between 3/8" to 1/2". Too much throw will damage the solenoid. If the solenoid emits a loud buzzing sound when the motor is run, the brake must be adjusted.
- 6. In operators which have a disconnect handle, inspect disconnect handle for proper function and lubricate if necessary. Use a lithium based grease on all moving parts.
- 7. Inspect all nuts and bolts for proper tightness and tighten as necessary.
- 8. Check all reversing devices for proper function. Inspect all contact edges for wear and replace if required. Check photoeyes for proper alignment and function.
- 9. Check current sensing for proper adjustment when finished with inspection and maintenance.
- 10. Inspect the installation area. Are all the warning signs intact and visible? If they are missing or need replaced, contact Linear. Be sure there are no control stations mounted within reach of the gate. Review safety literature with the customer and advise them to remove any such stations found.

### **FCC Notice**

This device complies with FCC Rules Part 15 and Industry Canada Rules & Regulations. Operation is subject to the following two conditions: (1) This device may not cause harmful interference and (2) this device must accept any interference received, including interference that may cause undesired operation.





MODEL SWG MECHANICAL PARTS LIST			
REF. #	PART #	DESCRIPTION	
	2120-361	Complete Enclosure Assembly with Door	
1	2110-067	Enclosure Assembly without Door	
	2120-362	Enclosure Door and Lock Assembly	
	2110-643	Snap Lock Assembly only	
2	2110-161	Mounting Panel Assembly	
3	2100-708	Side Support Bracket	
4	2100-656	Side Plate, 3/8"	
5	2200-264	Pillow Block Bearing	
6	2100-766	Drive Shaft, 1-1/8" diameter	
8	2400-278	Key, 1/4" x 1/4" x 2-1/2"	
9	2200-595	Torque Limiter, 5"	
	2300-381	Torque Limiter Facing, 5"	
10	2200-583	Sprocket, 40-A-36, 3" bore	
11	2210-009	Sprocket, 48-B-30, 1-1/8" bore	
13	2100-1112-PLT	Moisture Seal Spacer (2)	
14	2200-016	Moisture Seal	
15	2400-067	Seal Washer, 1" x 2-1/2"	
18	2200-097	Gear Reducer, 60:1	
19	2200-968	Sprocket, 40-B-22, 1" bore	
20	2100-735	Limit Box Mounting Plate	
21	2520-453	Rotary Limit Box Assembly	
22	2200-008	Sprocket, 48-B-10, 1/2" bore	
23	2200-459	#40 Roller Chain, 27 1/2 Links	
24	2200-006	#40 Master Link	
25	2200-200	#48 Roller Chain, 27 Links	
26	2200-010	#48 Master Link	
27		Complete Controller Assembly	
28	2200-409	Pipe Nipple	
29	2100-1414	Reducer Plate	
30	2100-1413	Reducer Plate Spacer	
	2200-428	Reducing Coupling	
	2200-429	Pipe, 1/4" x 3 1/2" THD, both ends	
	2400-264	Pipe Plug, 1/4"	
	2510-064	Three-Button Station with Lead Wires	
	2500-033	Three-Button Station only	
31	2400-514	Retaining Ring Clip	
		C-Face Motors	
	2500-2313	1/2 HP, 208/230/460V, 3 Phase	
17	2500-2315	1 HP, 208/230/460V, 3 Phase	
	2500-372	2 HP, 208/230/460V, 3 Phase	

### **Controller Parts List**



VS-GSWG CONTROLLER MECHANICAL PARTS LIST				
REF. #	PART # DESCRIPTION			
	Variable Speed Control Box Assemblies			
	2520-543	1/2 HP, 115V, 1-Phase Controller		
	2520-544	1/2 HP, 208/230V, 1-Phase Controller		
	2520-545	1/2 HP, 208/230V, 3-Phase Controller		
	2520-546	1/2 HP, 460V, 3-Phase Controller		
	2520-547	1 HP, 115V, 1-Phase Controller		
	2520-548	1 HP, 208/230V, 1-Phase Controller		
	2520-549	1 HP, 208/230V, 3-Phase Controller		
	2520-550	1 HP, 460V, 3-Phase Controller		
	2520-551	2 HP, 208/230V, 1-Phase Controller		
	2520-552	2 HP, 208/230V, 3-Phase Controller		
	2520-553	2 HP, 460V, 3-Phase Controller		
1	2120-447	Enclosure with Cover		
Transformers				
	2500-212	115V to 24V, 40VA		
2	2500-791	208/230V to 24V, 40VA		
	2500-214	460V to 24V, 40VA		

REF. #	PART #	DESCRIPTION		
Hitachi Controllers				
	2500-2244	1/2 HP, 115V, 1-Phase		
	2500-2246	1/2 HP, 208/230V, 1-Phase or 3-Phase		
	2500-2249	1/2 HP, 460V, 3-Phase		
0	2500-2245	1 HP, 115V, 1-Phase		
3	2500-2247	1 HP, 208/230V, 1-Phase or 3-Phase		
	2500-2250	1 HP, 460V, 3-Phase		
	2500-2248	2 HP, 208/230V, 1-Phase or 3-Phase		
	2500-2251	2 HP, 460V, 3-Phase		
		Apex Parts		
4	2500-1980	3-Phase Motor Board		
5	2100-2149	Apex Mounting Straps		
6	2500-2393	Apex Module		
8	2500-2291	Power On/Off Switch, 30 Amp, 600VAC		
	Wiring Harnesses			
9	2510-494	Limit Switch Harness		
10	2510-500	Control Box Motor Harness, 115/230V		
10	2510-501	Control Box Motor Harness, 460V		

### **Variable Speed Drive Programming**

This unit has been programmed at the factory. No changes should be necessary for normal operation. PLEASE CONSULT THE FACTORY BEFORE MAKING ANY CHANGES!

#### Programming the Hitachi Inverter

- 1. Apply power
- 2. Press FUNC
- 3. Use ▲▼ arrows to advance to F\_\_ (F002 for L200)
- 4. Press FUNC arrow to get to F02 (L100 ONLY)
- 5. Press FUNC, arrows to change to 3.0 (3.00 for L200), STR
- Up arrow to advance to next parameter, (F03), FUNC to view, arrows to change, STR to store and continue, advance through listed parameters and store new values.
- To switch from one letter prefix to another, press FUNC 3 times, advance to desired letter prefix, press FUNC, advance to desired parameter.
- When all parameters have been changed, advance to D01, press FUNC, then press STR. This will display the operating speed in Hz. (0-95)



Figure 14. Hitachi L200 Inverter

List of parameters set at factory					
MODEL L100		MODEL L200			
FUNCTION	DESCRIPTION	RECOMMENDED SETTING	FUNCTION	DESCRIPTION	RECOMMENDED SETTING
F02	ACCEL TIME	3.0	F002	ACCEL TIME	3.00
F03	DECEL TIME	3.0	F003	DECEL TIME	3.00
A01	SPEED SOURCE	00 (POT)	A001	SPEED SOURCE	00 (POT)
A02	RUN COMMAND SOURCE	01	A002	RUN COMMAND SOURCE	01
A04	MAX SPEED	95.0 (Hz)	A004	MAX SPEED	95 (Hz)
A20	TARGET SPEED	95.0 (Hz)	A020	TARGET SPEED	95.0 (Hz)
A21	SECOND SPEED	20.0 (Hz)	A021	SECOND SPEED	20.0 (Hz)
			A042	AUTO TORQUE BOOST	0
			A044	BOOST PERCENT	00
			A081	AUTO VOLTAGE REGULATION	01
A62	MIN SPEED	20.0 (Hz)	A062	MIN SPEED	20.0 (Hz)
B01	AUTO RESET	01	B001	AUTO RESET	01
			B130	INHIBIT DECEL OVERVOLTAGE	01
C03	TERM 3 FUNC	03	C003	TERM 3 FUNC	03
C04	TERM 4 FUNC	11	C004	TERM 4 FUNC	11
			C014	TERM 4 STATE	01



GATE ARM ASSEMBLY MECHANICAL PARTS LIST			
REF. #	PART #	DESCRIPTION	
	2110-648	Gate Arm Assembly, 78" (complete)	
1	2110-312	Welded Rail Assembly, 78"	
9	2110-248	Upper Rail Guide Assembly, with Bearing	
12	2220-011	Sprocket, 40-B-13, 7/8" bore, with Bearing	
13	2200-004	Sprocket, 40-B-13, 1" bore	
14	2400-026	Spring Pin, 3/16" x 1"	
15	2100-051	Lower Rail Guide	
16	2100-052	Rain Cover	
19	2400-004	Key, 1/4" x 1/4" x 1"	
22	2100-054	Chain Tension Bolt	
23	2400-015	Hex Nut, 3/8"-16	
24	2200-006	#40 Master Link	
25	2200-658	#40 Chain, 72 Links	
26	2100-1168-BT	Cover for 78" Arm	
	Parts for non-st	andard 63" VS-GSWG Gate Arm	
	2110-257	Gate Arm Assembly, 63" (complete)	
1	2110-271	Welded Rail Assembly, 63"	
25	2200-420	#40 Chain, 57 Links	
26	2100-1167-BT	Cover for 63" Arm	

This page left blank intentionally.

### **Gate Operator Installation Checklist**

INSTALLER	CUSTOMER		
		1.	The gate has been checked to make sure it is level and moves freely in both directions.
		2.	Potential pinch areas have been guarded so as to be inaccessible <b>OR</b> have contact and/or non-contact obstruction sensing devices installed.
		3.	The installer has installed one or more contact or non-contact obstruction sensing devices, in compliance with UL325 requirements for this installation.
		4.	If pedestrian traffic is expected, a separate pedestrian gate has been installed, a minimum of seven feet from the gate. The customer has been informed that all pedestrian traffic must use the pedestrian gate.
		5.	Warning signs have been installed on each side of the gate in highly visible locations. The customer has been informed that these signs must remain at all times.
		6.	There are no controls installed on the gate operator, or within seven feet of the gate.
		7.	The installer has properly adjusted the obstruction sensing feature and has tested the gate to make sure that the gate stops and reverses a short distance with minimal resistance applied (40 lbs. on a swing gate at the end of the gate, 75 lbs. on a slide gate)
		8.	The installer has instructed the customer in the proper use of the gate operator and reviewed all of the operational functions, obstruction sensing devices, warning beeper and reset, etc.
		9.	The installer has instructed the customer in the proper use of the operator's manual disconnect feature. The manual disconnect must never be used while the gate is in motion. The power switch must be turned off before using the manual disconnect and disengaging the operator.
		10.	The installer has reviewed all safety instructions with the customer, and has left the safety instructions and owner's information sheets for their reference.
		11.	The installer has answered any questions the customer has regarding the operation of the gate operator and gate operator safety precautions.
		12.	The installer has explained to the customer that a regular maintenance schedule for both the gate and the gate operator is recommended.

By signing this installation checklist, I/we hereby certify that each item listed and checked above has been covered by the installer and is clearly understood by the customer.

Customer's Signature	Date
Installer's Signature	Date

VS-GSWG Swing Gate Operator Installation Guide